

Embedded Linux Conference Europe 2018

三菱電機におけるOSS自動試験活用のご紹介

三菱電機(株) 情報技術総合研究所
リアルタイムプラットフォーム技術部
茂田井寛隆

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OUTLINE

- Who I am
- Overview
- Related Tools
 - Automated Test Framework / Fuego
 - Real-time latency tool / cyclicttest
 - Tracing kernel feature / ftrace
- Issue
- Approach
 - Our Use Cases
- Conclusion and Future work

本資料はEmbedded Linux Conference Europe 2018にて
発表された資料です

WHO I AM

- Hirotaka MOTAI
 - Software Researcher for embedded systems of Mitsubishi Electric Corp.
- We have collaborated with LF projects.
 - LTSI: Long Term Support Initiative
 - AGL : Automotive Grade Linux
 - FUEGO: Test framework
 - Specifically designed for testing Embedded Linux



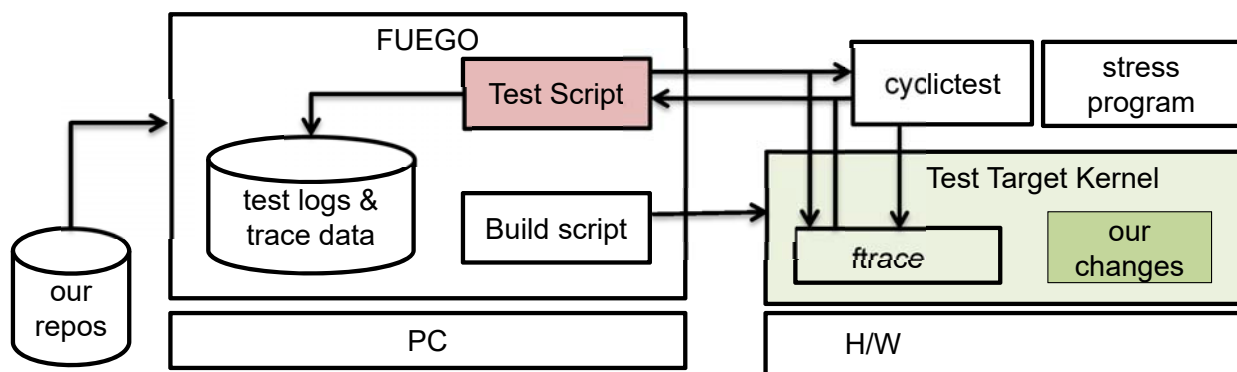
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OVERVIEW

- Linux can be adapted to various embedded devices, even though they need a hard real-time response.
- We need tons of time to ensure adequate real-time performance.
 - Real-time applications need to satisfy timing constraints.
 - We have to avoid kernel changes which might cause long delays.

OVERVIEW

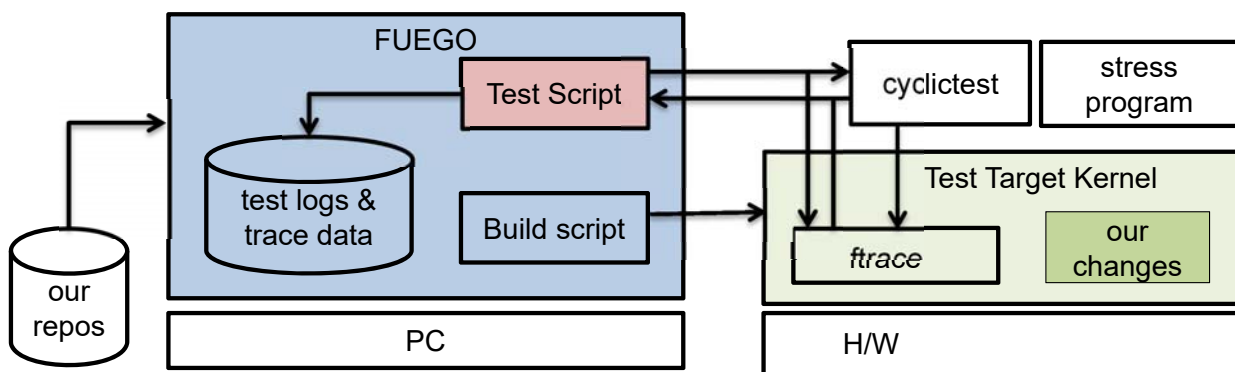
- I have developed a new test script on Fuego.
 - measure the real-time performance, plus get tracing.
 - get clues to isolate the problem whether it was caused by our changes or not.



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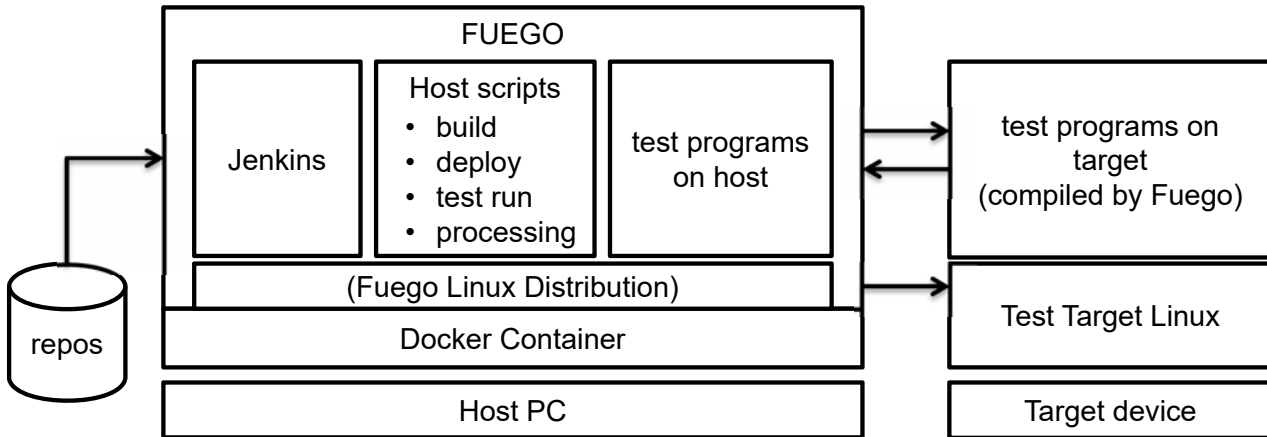
FUEGO

- Fuego is the automated test framework
 - created by LTSI project, based on Jenkins.
 - OSS: anyone can use and contribute!
 - AGL-JTA: AGL chose Fuego as standard test environment.



FUEGO

- Fuego = "test distribution + Jenkins + host scripts + pre-packaged tests" on container
- Fuego can do specific tests automatically that is triggered by software update.

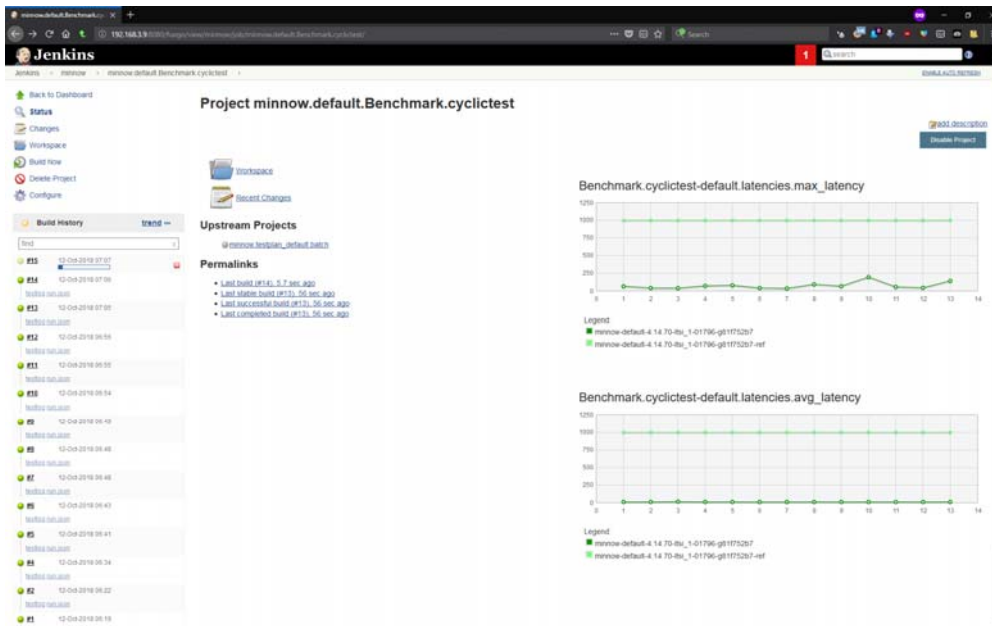


FUEGO

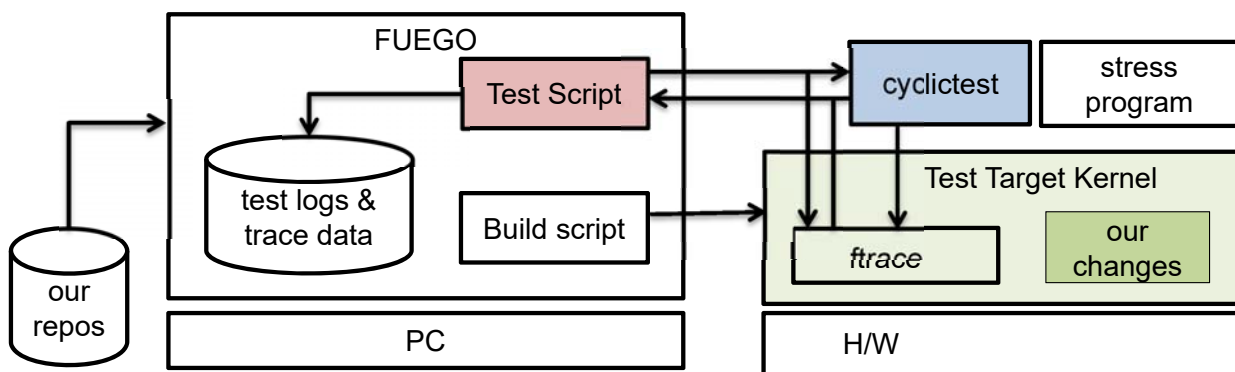
- You can click to start manually and monitor tests on Jenkins.

All	minnow	raspbian3				
S	W	Name ↓	Last Success	Last Failure	Last Duration	
🌞		minnow.default.Benchmark.bonnie	N/A	N/A	N/A	🎮
🟢	🌞	minnow.default.Benchmark.cyclictst	4 min 26 sec - #17	N/A	37 sec	🎮
🌞		minnow.default.Benchmark.dbench4	N/A	N/A	N/A	🎮
🌞		minnow.default.Benchmark.Dhrystone	N/A	N/A	N/A	🎮
🌞		minnow.default.Benchmark.ebizzy	N/A	N/A	N/A	🎮
🌞		minnow.default.Benchmark.ffsb	N/A	N/A	N/A	🎮
🌞		minnow.default.Benchmark.fio	N/A	N/A	N/A	🎮
🌞		minnow.default.Benchmark.GLMark	N/A	N/A	N/A	🎮
🌞		minnow.default.Benchmark.gtkperf	N/A	N/A	N/A	🎮
🌞		minnow.default.Benchmark.hackbench	N/A	N/A	N/A	🎮
🌞		minnow.default.Benchmark.himeno	N/A	N/A	N/A	🎮
🌞		minnow.default.Benchmark.interbench	N/A	N/A	N/A	🎮

- You can also check test results on Jenkins.

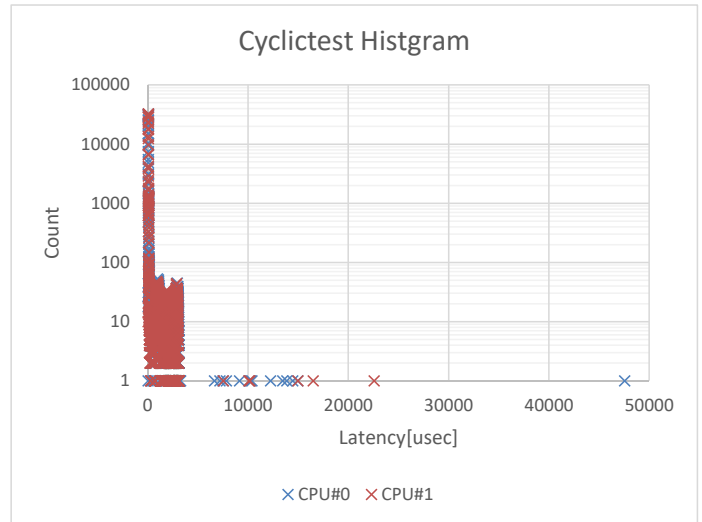
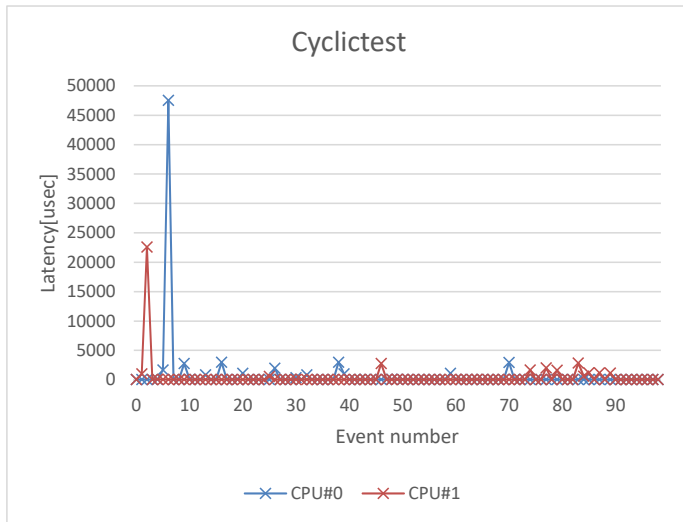


- What is Cyclictest?
 - Benchmark tool for interval timer latency.
 - Refer to: <https://wiki.linuxfoundation.org/realtime/documentation/howto/tools/cyclictest>



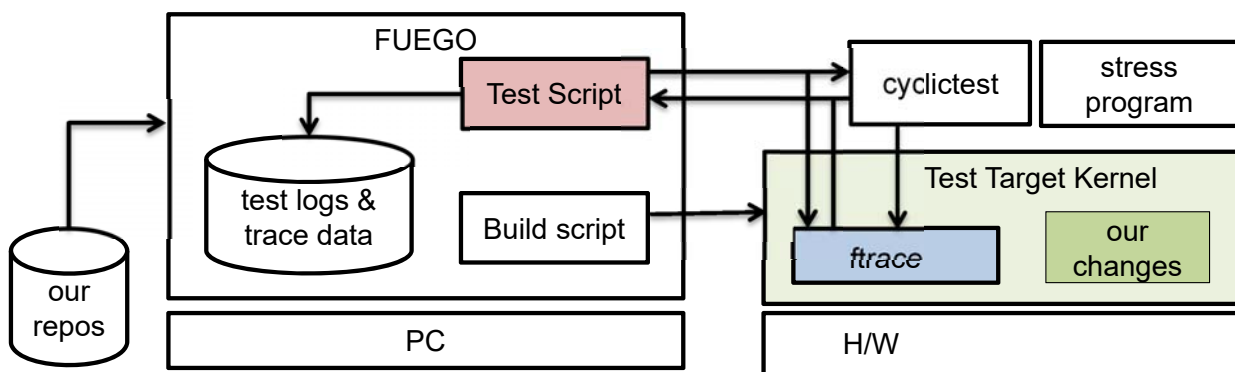
CYCLICTEST

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FTRACE

- Ftrace have been in the kernel since Linux v2.6.27.
- Traces kernel without recompiling.
- Useful for data gathering, debugging, and performance tuning.
- Detailed in Documentation/trace/index.rst



- The Function Tracer

```
# tracer: function
#
#          _-----> irqsoft
#         / _-----> need-resched
#        | / _-----> hardirq/softirq
#       || / _--=> preempt-depth
#      ||| /      delay
#     TASK-PID  CPU#  ||||   TIMESTAMP  FUNCTION
#     | |       |   |   |   |          |          |
stress-ng-shm-s-1257 [000] ....  7523.267555: vmacache_find <-find_vma
stress-ng_1h_pl-1194 [001] ....  7523.267556: mutex_unlock <-
                                     rb_simple_write
stress-ng-shm-s-1257 [000] ....  7523.267559: handle_mm_fault <-
                                     __do_page_fault

[snip]
```

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minnow.default.Benchmark.cyclictest

Jenkins

Workspace

Build Now

latencies.max_latency

#21 12-Oct-2018 07:52

testlog run ison

add description

Disable Project

ENABLE AUTO REFRESH

What changes have occurred the delay ?

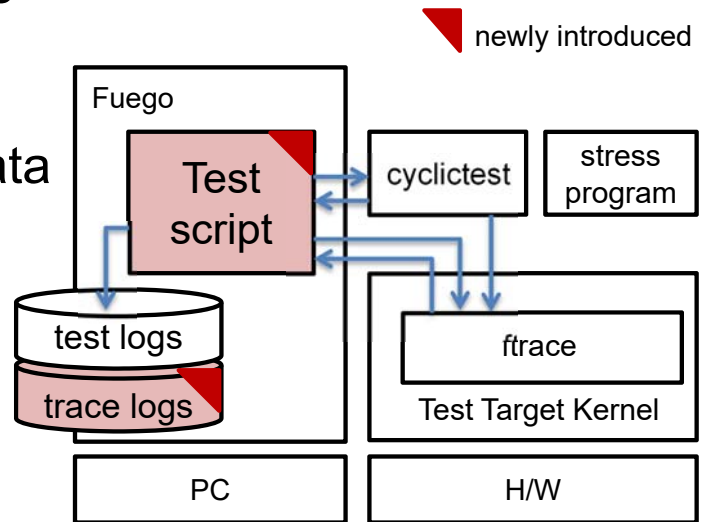
- Our changes?
- Potential performance issues?

It is necessary to save a trace log to isolate the problem.

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Our Approach

- Do in a simple way.
 - Script-based Test driver program
 - 1: setup ftrace configurations
 - 2: run stress program
 - 3: run cyclicttest
 - 4: save a log with a ftrace data
- Cyclicttest option
 - "--breaktrace breaktime[us]" can stop tracing when latency > breaktime



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STOP TRACING

- But, --breaktrace option will stop not only tracing but also testing, when diff > breaktime.

```

873     if (!stopped && t && (diff > tracelimit)) {
874         stopped++;
875         tracemark("hit threshold (%llu > %d)",
876                 (unsigned long) diff, tracelimit);
877         shutdown++;
878         pthread_mutex_lock(&break_thread_id_lock);
879         if (break_thread_id == 0)
880             break_thread_id = stat->tid;
881         break_thread value = diff;

```

Annotations in the code block:

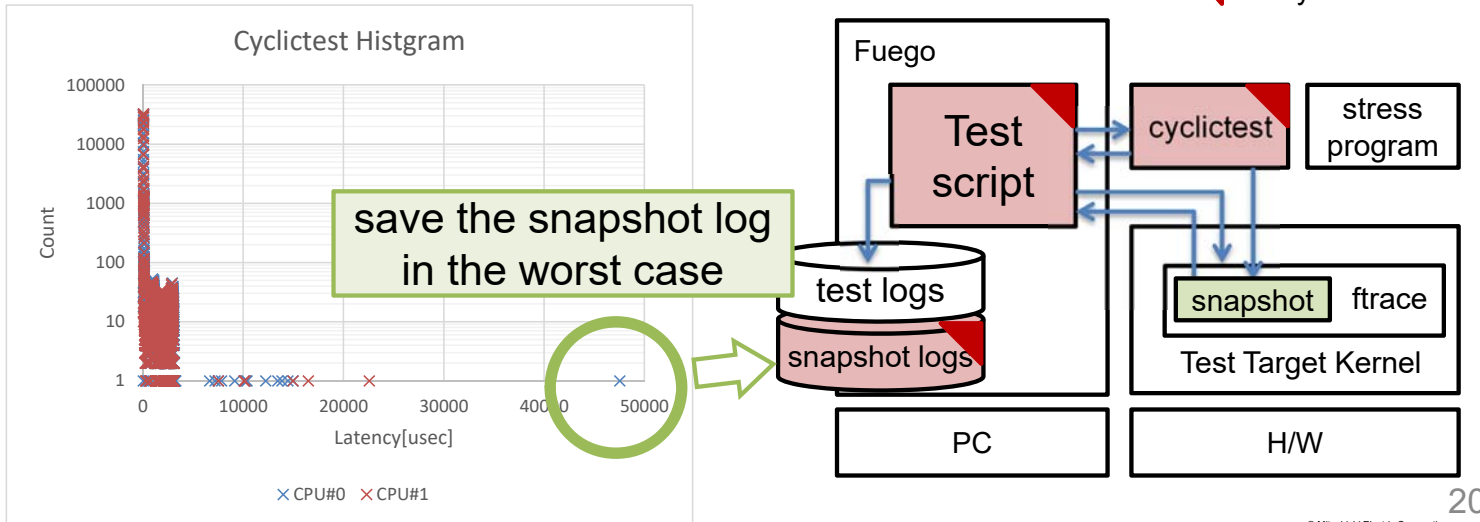
- A callout box labeled 'stop tracing' points to the condition `t && (diff > tracelimit)`.
- A callout box labeled 'stop testing' points to the `shutdown++` line.

The record may not be the worst case... k);

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Improved Approach

- Using a ftrace feature "Snapshot"
 - Cyclicttest is modified to take a snapshot when maximum-latency is updated.



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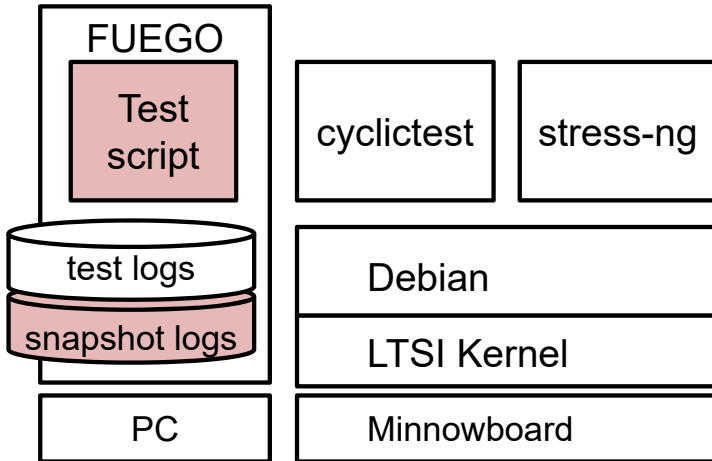
OUR ACTUAL CASE WITH AN IMPROVED APPROACH...

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Detail of Our Evaluation Environment

- Our test case

- Latency of real-time priority process under some kinds of stress by non-realtime process.



- Cyclicttest with realtime priority
- Stress-ng with non-realtime priority
 - making stressful

Hardware and OS

- Target board: Minnowboard Turbot Dual-core

- Intel Atom E3826
 - #Cores / Threads: 2/2
 - Freq / Cache : 1.46GHz / 1MB

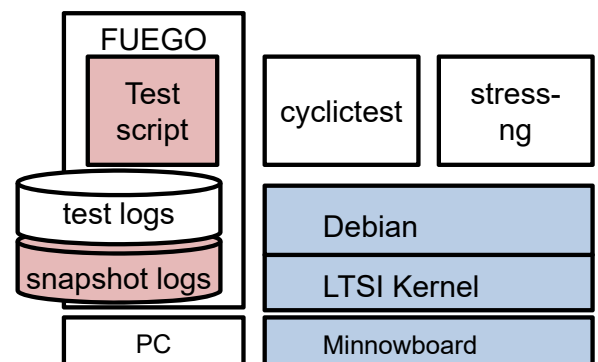
- 2GB DDR3L 1067MT/s

- Storage: microSD

- Ethernet: Intel i211

- Debian Gnu/Linux 9.5.0

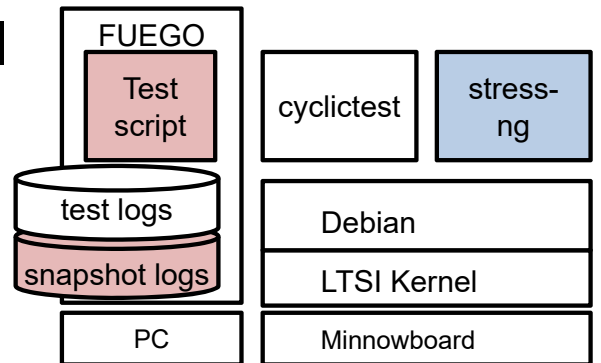
- Linux 4.14 LTSI



Stress-ng

- stress-ng has stressors for a lot of components
 - cpu, fork, timer, sync, dentry, flock, udp, pipe, semaphore...
 - Beware, extreme scenarios seldom happen in real-life.

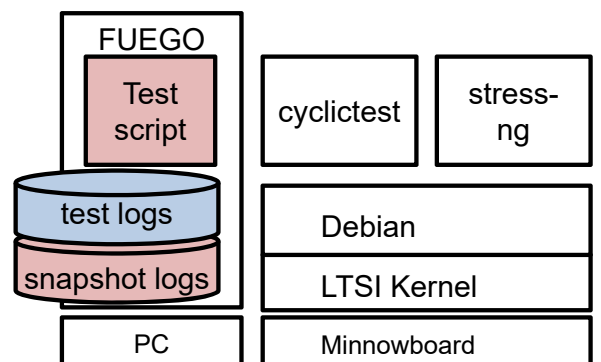
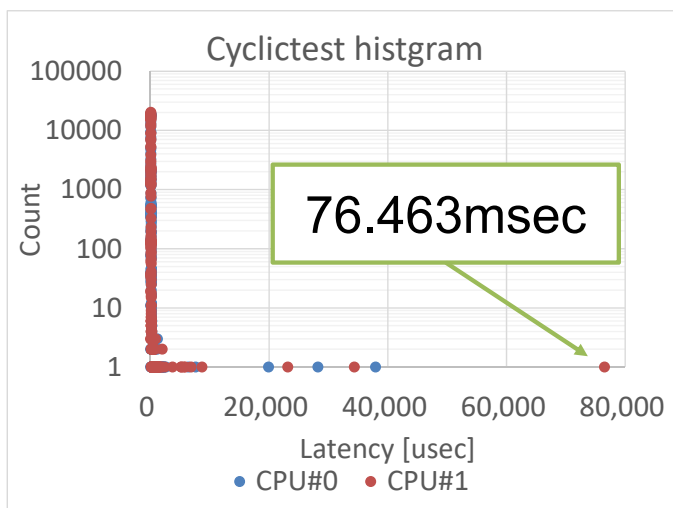
• \$./stress-ng --stressors | wc -l
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Result

- Stress-ng
 - Create&delete directory entry (dentry), 8 instances without CPUSET, with non-realtime priority.
 - 1 hour



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Result

- Snapshot log in the worst case.

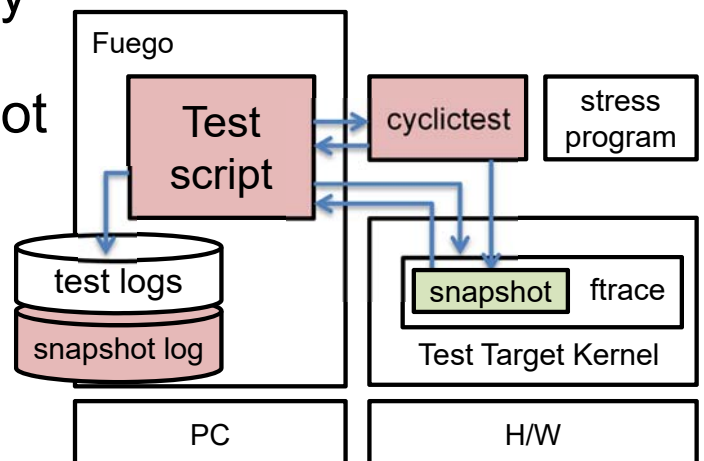
```

cyclictest-17361 [001] .... 55024.413733: mutex_lock <-__fdget_pos
cyclictest-17361 [001] .... 55024.413733: vfs_write <-SyS_write
cyclictest-17361 [001] .... 55024.413734: rw_verify_area <-vfs_write
cyclictest-17361 [001] .... 55024.413735: security_file_permission <-
    rw_verify_area
cyclictest-17361 [001] .... 55024.413736: __sb_start_write <-vfs_write
cyclictest-17361 [001] .... 55024.413737: ..._add <-
    ..._write
cyclictest-17361 [001] ...1 55024.413738: ..._sub <-
    __sb_start_write
cyclictest-17361 [001] .... 55024.413739: __vfs_write <-vfs_write
cyclictest-17361 [001] .... 55024.413741: tracing_mark_write: hit latency
    snapshot threshold (76463 > 1000)
cyclictest-17361 [001] .... 55024.413745: __fsnotify_parent <-vfs_write
cyclictest-17361 [001] .... 55024.413746: fsnotify <-vfs_write
  
```

76.463msec

Evaluation

- We got clues to detect the factor by doing a test and tracing at the same time.
- Fuego helped repeat execution of both.
- Therefore, we can effectively figure out the reason of the delay with using the snapshot log.



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CONCLUSION

- Summary
 - It is important to ensure adequate performance before releasing products.
 - It is necessary to repeat tests for reproducing the rare case which does not meet real-time performance requirements.
 - Fuego is useful to us for not only measuring but also tracing at the same time.
- Future Works
 - Discussion with Fuego community for adding our test script which I have shown.

- Test Framework: FUEGO
 - <http://fuegotest.org/>
 - <https://elinux.org/Fuego>
- LTSI Project
 - <https://ltsi.linuxfoundation.org/>
- AGL Test framework: AGL-JTA
 - <https://wiki.automotivelinux.org/agl-jta>
- rt-tests
 - <https://wiki.linuxfoundation.org/realtime/documentation/howto/tools/rt-tests>
- stress-ng
 - <http://kernel.ubuntu.com/~cking/stress-ng/>

APPENDIX

Use Case: Cyclicttest Options

- 1 msec latency, 10 msec interval, in 1 hour.
 - \$ cyclicttest
 - --histogram=10000 --interval=10000 --duration=3600s
 - --smp --quiet --mlockall --priority=50
 - --snapshot=1000 (instead of --breaktime)

Use Case: Test Script

- Test script runs on target.
 - 1: chrt itself
 - 2: run stress-ng program as non-rt process
 - 3: maximize /proc/sys/kernel/sched_rt_runtime_us
 - 4: setup ftrace configurations
 - echo 0 > \$ftracedir/tracing_on
 - echo 0 > \$ftracedir/snapshot
 - echo function > \$ftracedir/current_tracer
 - echo 1 > \$ftracedir/tracing_on
 - 5: run cyclicttest
 - 6: save the log and a snapshot data (if recorded) to Fuego
 - 7: normalize /proc/sys/kernel/sched_rt_runtime_us